#### New bulk scalar field solutions in brane worlds

M. Parry and S. Pichler

Theoretische Physik, Ludwig-Maximilians-Universität, Theresienstr. 37, 80333 München, GERMANY

We use nonlinear perturbation theory to obtain new solutions for brane world models that incorporate a massive bulk scalar field. We then consider tensor perturbations and show that Newtonian gravity is recovered on the brane for both a light scalar field and for a bulk field with large negative mass. This latter result points to the viability of higher-derivative theories of gravity in the context of bulk extra dimensions.

#### I. INTRODUCTION

One of the unsatisfying features of the Randall-Sundrum models has always been the need to fine-tune the brane tension and the bulk cosmological constant. Immediately after these models were proposed, many authors considered adding bulk scalar fields in order to evade this problem. It was hoped that the brane-bulk system would also be stabilized by the presence of these fields. However, it has proved difficult to find self-consistent analytic solutions to all but the simplest scenarios, e.g. superpotential models [1, 2, 3]. Furthermore, the order of complexity rises when one considers a fully time-dependent scenario. For this reason, work has recently been concentrated on numerical simulations [4].

On the other hand, the insight of Randall and Sundrum was that gravity can still be effectively 4-dimensional despite the presence of a fifth, spatial dimension. Therefore, if one complicates their simple models by including a bulk scalar field, it is vital to ensure that gravity has the usual Newtonian limit, at the very least.

In this paper, we tackle analytically the case of brane worlds with a massive bulk scalar field. We conduct two distinct perturbative analyses. In the first, we utilize ideas in nonlinear perturbation theory to obtain leading corrections to the background warp factor and bulk field; it is the nature of the former that is crucial to the localization of gravity on the brane. Then, we consider metric and matter perturbations of the brane-bulk system, and compute the Green's function in response to a point-mass on the brane. We show that the Green's function has the required 1/r-behavior in the long-distance limit.

Although our presentation here is something of a mathematical proof-of-concept, it sets the stage for a subsequent paper that will explore these issues in the context of theories of higher-derivative gravity.

# II. BACKGROUND SOLUTIONS

We begin our analysis by considering the model of one Minkowski brane in a bulk that contains a massive scalar field  $\phi$ . The scalar field potential is  $V=\frac{1}{2}M^2\phi^2$ . The brane is coupled to the scalar field via its tension; to be specific, we choose a Liouville potential for the tension,  $\lambda(\phi)=e^{-2\phi/\sqrt{3}}$ . In fact, the explicit choice of  $\lambda(\phi)$  is not so important since we only ever need its value at

 $\phi(0)$ . Our choice effectively fixes the degree of freedom associated with  $\lambda'(\phi(0))$ .

The line-element for the brane-bulk system may be written as

$$ds^{2} = e^{2X(y)} \eta_{\mu\nu} dx^{\mu} dx^{\nu} - dy^{2}, \tag{1}$$

with the brane at y = 0. The equations of motion that follow from the Einstein field equations are

$$-3X_{yy} - 6X_y^2 = \frac{1}{2}\phi_y^2 + \frac{1}{2}M^2\phi^2, \tag{2}$$

$$6X_y^2 = \frac{1}{2}\phi_y^2 - \frac{1}{2}M^2\phi^2, \tag{3}$$

$$\phi_{yy} + 4X_y \phi_y = M^2 \phi. (4)$$

Note that we will often use a subscript to denote a derivative when there is no cause for confusion. The junction conditions at the brane position are

$$X_y(0) = -\frac{1}{6}, \quad \phi_y(0) = -\frac{1}{\sqrt{3}},$$
 (5)

where we have assumed  $\mathbb{Z}_2$ -symmetry—we evaluate quantities as  $y \downarrow 0$ —and used the fact that  $\phi(0) = 0$ , which follows from eq. (3). Without loss of generality, we choose X(0) = 0. Finally, we point out that we have made all quantities dimensionless by rescaling in terms of a characteristic length  $\lambda^{-1}(0)M_P^3$  and characteristic scalar field value  $M_P^{3/2}$ , where  $M_P$  is the 5-dimensional Planck mass.

### A. Small $M^2$

We let  $\epsilon=M^2$  be our perturbative parameter. Then, we introduce a "strained" coordinate,

$$x = (1 + \mu \epsilon)^{-1} y,\tag{6}$$

in place of y. This technique, known as the Lindstedt-Poincaré method [5], can make a divergent perturbative expansion convergent by an appropriate choice of  $\mu$ .

We now let  $X = X_0(x) + \epsilon X_1(x) + \dots$  and  $\phi = \phi_0(x) + \epsilon \phi_1(x) + \dots$ , and expand the equations of motion and junction conditions up to first order in  $\epsilon$ . The zeroth order equations yield

$$X_0 = \frac{1}{4} \ln \left( 1 - \frac{2}{3} x \right), \quad \phi_0 = 2\sqrt{3} X_0.$$
 (7)

The obvious feature of the solution is the singularity at  $x = \frac{3}{2}$ . It is easy to check that this is not a coordinate singularity; indeed, such singularities appear to be generic

in scalar field models [1, 2]. We will discuss what to do about them in subsection II C.

The first order equations are much more involved and we omit the expressions for  $X_1$  and  $\phi_1$ . We are not primarily interested in their contribution to the overall solution at this stage, but rather in what they imply about  $\mu$ . To make this last point more transparent, it is enough to know that the homogeneous solution to  $X_1$  is

$$X_1^{(h)} = A(\mu) + \frac{B(\mu)}{1 - \frac{2}{3}x},$$
 (8)

where A and B are constants. The problem is that the latter term will dominate  $X_0$ : even for small  $\epsilon$ , the warp factor  $e^X$  will pick up a term like  $(1 - \frac{2}{3}x)^{-3/4}$ . Such a term is sometimes called a secular term. The solution is to choose  $\mu$  so that  $B(\mu) = 0$ . It turns out that

$$\mu = -\frac{1}{6},\tag{9}$$

and then

$$X_0 = \frac{1}{4} \ln \left( 1 - \frac{\frac{2}{3}y}{1 - \frac{1}{6}\epsilon} \right). \tag{10}$$

Note that, even at zeroth order, an effect of the perturbation is seen. However, we now need the first order terms to ensure the junction conditions are satisfied. That the singularity occurs at  $y=\frac{3}{2}(1-\frac{1}{6}\epsilon)$ , is borne out by numerical simulations.

## B. Large $-M^2$

In this case, the convenient perturbative parameter is  $\epsilon = |M|^{-1}$ . The Lindstedt-Poincaré method is not required here, but because the  $\epsilon \to 0$  limit is problematic, it is also not obvious what perturbative expansion will work. From numerical observations, it is apparent that  $X \sim \frac{1}{2} \ln(1 - \frac{1}{3}y)$  but that highly oscillatory terms arise in  $X_y$  and  $X_{yy}$ . Curiously, the solution for X is what one would obtain in the usual Randall-Sundrum case with no bulk cosmological constant if eq. (3) could be ignored. Therefore, the limit we are considering here can be thought of as the best a scalar field can do to mimic  $\Lambda = 0$ . Note that, once again, there is a singularity at finite coordinate distance from the brane.

Expansions for X and  $\phi$  that capture the oscillatory nature of the solutions are as follows:

$$X = \frac{1}{2} \ln \left( 1 - \frac{1}{3} y \right) + \sum_{n=1}^{\infty} \epsilon^{2n} \left( 1 - \frac{1}{3} y \right)^{-2n} E_n \left( \frac{y}{\epsilon} \right), (11)$$

$$\phi = \sum_{n=1}^{\infty} \epsilon^{2n-1} \left( 1 - \frac{1}{3} y \right)^{-2n+1} F_n \left( \frac{y}{\epsilon} \right). \tag{12}$$

In fact, for our purposes, the first term under the summation will be sufficient. The important point, however, is that taking derivatives of these terms makes them of

lower order in  $\epsilon$ . The solutions of the equations resulting from substituting the above expansions into the equations of motion and the junction conditions are

$$E_1(u) = -\frac{1}{36}\sin^2 u, \quad F_1(u) = -\frac{1}{\sqrt{3}}\sin u.$$
 (13)

## C. Eliminating the singularity

As pointed out above, the presence of singularities in our solutions is both generic and problematic. The standard method of dealing with them is to add a "regulator" brane to the system. If the singularity is at  $y=y_s$ , then placing the second brane at  $y=y_\star < y_s$  will, due to  $\mathbb{Z}_2$ -symmetry, "slice off" the section  $y>y_\star$ , which includes the singularity.

The insertion point  $y_{\star}$  is not arbitrary, however. If we let the brane tension of the regulator brane be  $\lambda_{\star}(\phi)$ , then a second set of junction conditions which must be satisfied are

$$X_y(y_*) = \frac{1}{6}\lambda_*(\phi), \quad \phi_y(y_*) = -\frac{1}{2}\lambda_*'(\phi), \tag{14}$$

where all quantities are evaluated as  $y \uparrow y_{\star}$ . In what follows, we will assume that these conditions are met. The subsequent question of whether the two-brane setup can be stabilized is left for a future numerical study.

#### III. TENSOR PERTURBATIONS

Having obtained the background solutions, we are now interested in perturbing about them. In particular, we focus on tensor perturbations in the brane-bulk system in order to understand the nature of gravity for a brane-bound observer.

The most convenient framework in which to describe perturbations is the explicitly conformal line-element

$$ds^{2} = a^{2}(Y) \left( \eta_{\mu\nu} dx^{\mu} dx^{\nu} - dY^{2} \right)$$
 (15)

that follows from transforming line-element (1) to a new coordinate:  $Y = \int_0^y e^{-X(y')} dy'$ . The warp factor is  $a(Y) = e^{X(y)}$ . The gauge-invariant tensor perturbations decouple from the scalar and vector perturbations, and take the form

$$\delta g_{\mu\nu}^{(T)} = a^2 h_{\mu\nu}, \quad \delta g_{\mu 5}^{(T)} = \delta g_{55}^{(T)} = 0,$$
 (16)

where indices on  $h_{\mu\nu}$  are raised (lowered) by  $\eta^{\mu\nu}(\eta_{\mu\nu})$  and  $h_{\mu\nu}$  is transverse traceless:

$$h^{\mu}{}_{\mu} = \partial_{\mu} h^{\mu}{}_{\nu} = 0. \tag{17}$$

The only wrinkle in this otherwise straightforward setup is that one must also consider perturbation in the brane positions [6]. To be precise, there is a scalar degree of freedom associated with each brane, which adds an additional term to the perturbed junction conditions.

If there were only one brane and no matter perturbation on it, the perturbation in position could simply be eliminated by a redefinition of the coordinates. In our scenario, we will suppose there is no matter perturbation on the second brane and consider its position fixed. On the other hand, we wish to calculate the gravitational response to a point-mass on the first brane and thus its position, here corresponding to the radion, must be perturbed.

### A. Equations of motion

In terms of our new coordinate, the original unperturbed brane is located Y=0. We now suppose it is perturbed to  $Y=\zeta(x^{\mu})$ —to first order,  $y=\zeta(x^{\mu})$  also—following a general matter perturbation given by the energy-momentum tensor  $\tau_{\mu\nu}$ . The resulting equations of motion for the tensor modes are

$$\left(\partial_Y^2 + 3\frac{a_Y}{a}\partial_Y - \Box\right)h_{\mu\nu} = 0,\tag{18}$$

subject to the junction conditions

$$\partial_Y h_{\mu\nu}|_{Y=0} = \tau_{\mu\nu} - \frac{1}{3}\eta_{\mu\nu}\tau - 2\zeta_{,\mu\nu} \equiv \sigma_{\mu\nu}, \quad (19)$$

$$\partial_Y h_{\mu\nu}|_{Y\uparrow Y_{\bullet}} = 0. (20)$$

Because there are two conditions, we expect only a discrete set of gravitational modes.

The fact that the left-hand side of (19) is traceless gives us the important equation for the displacement of the brane [6], namely

$$\Box \zeta = -\frac{1}{6}\tau. \tag{21}$$

If we assume  $\partial_{\mu}\tau^{\mu}_{\ \nu}=0$ , then the transverse nature of  $h_{\mu\nu}$  is reflected in eq. (21) as well. In principle, we must solve this equation and substitute the solution into eq. (19). However, in this paper, we will content ourselves with computing the appropriate Green's function from which  $h_{\mu\nu}$  can be constructed.

### B. Green's function solution

Equations (18), (19) and (20) can be conveniently combined as

$$\left(\partial_Y^2 + 3\frac{a_Y}{a}\partial_Y - \Box\right)h_{\mu\nu} = 2\sigma_{\mu\nu}(x)\delta(Y),\tag{22}$$

allowing us to write a formal solution in terms of the retarded Green's function given by

$$\left(\partial_Y^2 + 3\frac{a_Y}{a}\partial_Y - \Box\right)G(x, x', Y, Y') = \delta^{(4)}(x - x')\delta(Y - Y'). \tag{23}$$

After a Fourier transform, this becomes a 1-dimensional Green's function problem

$$\hat{D}_k \tilde{G}(Y, Y') \equiv \left(\partial_Y^2 + 3\frac{a_Y}{a}\partial_Y + k^2\right)\tilde{G} = \delta(Y - Y'), \quad (24)$$

which can be solved in terms of the complete set of normalized eigenfunctions of  $\hat{D}_k$ .

To be precise, we suppose  $\hat{D}_k \chi_m = (k^2 - m^2) \chi_m$ , with boundary conditions  $\partial_Y \chi_m(0) = \partial_Y \chi_m(Y_\star) = 0$ . (These boundary conditions reflect both the continuity of  $\partial_Y \chi_m$  and the requirement of  $\mathbb{Z}_2$ -symmetry.) Then, introducing  $\psi_m = a^{3/2} \chi_m$ , we obtain the Schrödinger-like equation

$$\left(\partial_Y^2 + m^2 - \frac{(a^{3/2})_{YY}}{a^{3/2}}\right)\psi_m = 0.$$
 (25)

This is usefully rewritten as [7]

$$(\hat{D}_{+}\hat{D}_{-} + m^{2})\psi_{m} = 0, (26)$$

where

$$\hat{D}_{\pm} = \partial_Y \pm \frac{3}{2} X_Y. \tag{27}$$

The boundary conditions on the  $\psi_m$  can be written as  $\hat{D}_-\psi_m(0)=\hat{D}_-\psi_m(Y_\star)=0$ , and the eigenfunction normalization is  $2\int_0^{Y_\star}dY\;\psi_m\psi_n=\delta_{mn}$ . Then,

$$\tilde{G}(Y,Y') = \sum_{m} a^{-3} \frac{\psi_m(Y)\psi_m(Y')}{k^2 - m^2}.$$
 (28)

The information we particularly want from the Green's function is the response, in the stationary limit, at position  $\mathbf{x}$  on the brane due to a disturbance at  $\mathbf{x}'$  also on the brane. We have

$$G(\mathbf{x}, \mathbf{x}') = \int dt' \int \frac{d^4k}{(2\pi)^4} \tilde{G}(0, 0) e^{ik_{\mu}(x^{\mu} - x'^{\mu})}$$

$$= -\int \frac{d^3k}{(2\pi)^3} \sum_{m} \frac{\psi_m^2(0)}{\mathbf{k}^2 + m^2} e^{-i\mathbf{k}\cdot(\mathbf{x} - \mathbf{x}')}$$

$$= -\frac{1}{4\pi r} \sum_{m} \psi_m^2(0) e^{-mr}, \qquad (29)$$

where  $r = |\mathbf{x} - \mathbf{x}'|$ . A similar analysis was carried out in [8].

## C. Recovering the Newtonian limit

Inspection of eq. (29) shows we obtain the necessary leading 1/r-behavior if there is a zero mode. The contribution of other modes may spoil this result if there are tachyon modes, or if there are modes with  $mr \ll 1$ . This latter scenario is model-dependent but we can show [7] that there is always a zero mode and never a tachyon mode, i.e.  $m^2 \geq 0$ .

Multiplying eq. (26) by  $\psi_m$  and integrating over Y gives

$$m^{2} = -2 \int_{0}^{Y_{\star}} dY \, \psi_{m} \hat{D}_{+} \hat{D}_{-} \psi_{m}$$
$$= -2 \psi_{m} \hat{D}_{-} \psi_{m} \mid_{0}^{Y_{\star}} + 2 \int_{0}^{Y_{\star}} dY \, (\hat{D}_{-} \psi_{m})^{2}. (30)$$

The first term is zero by the boundary conditions and the second term is non-negative. Furthermore, the zero mode is given by  $\hat{D}_{-}\psi_{0}=0$ , that is

$$\psi_0 \propto a^{3/2}.\tag{31}$$

### IV. GRAVITY AND A MASSIVE BULK SCALAR FIELD

We now apply the above formalism to the specific background solutions computed in section II. In both cases, small  $M^2$  and large  $-M^2$ , we will concentrate on the situation at zeroth order in  $\epsilon$ . For a start, as we have seen, nonlinear perturbation theory already gives perturbative effects at zeroth order, and secondly, because eq. (25) is of Schrödinger-type, it is straightforward, though hardly illuminating, to compute perturbative corrections to the  $\psi_m$ . We will assume that  $Y_\star \ll r$  and call this the long-distance limit.

### A. Small $M^2$

In this limit, we cannot completely ignore the first order term in our solution for X because it is necessary for getting the boundary condition at Y = 0 right. However, to a good approximation, we may account for  $X_1$  by simply rescaling  $X_0$ :

$$X \simeq \frac{1}{4}B\ln\left(1 - \frac{2}{3}B^{-1}y\right),$$
 (32)

where  $B = 1 - \frac{1}{6}\epsilon$ . It follows that

$$a \simeq \left(1 - \frac{Y}{Y_s}\right)^{Y_s/6},\tag{33}$$

with  $Y_s = 2 - \frac{4}{9}\epsilon$  to first order in  $\epsilon$ . The solutions to eq. (25) are then built from linear combinations of Bessel functions of the first and second kind:

$$\psi_m = (Y_s - Y)^{1/2} \mathcal{J}_p (m(Y_s - Y)),$$
 (34)

where  $p = \frac{1}{4}(Y_s - 2) \simeq -\frac{1}{9}\epsilon$ . The boundary conditions become  $\mathcal{J}_{p+1}(mY_s) = \mathcal{J}_{p+1}(m(Y_s - Y_\star)) = 0$ . In the limit of large  $mY_s$ , we find

$$\Delta m = \pi Y_{\star}^{-1} > \pi Y_{s}^{-1} \gg r^{-1}, \tag{35}$$

and therefore that the infinite tower of states will not seriously alter (29). The Newtonian limit will also not be affected by light modes: there is no massive bound state in the limit of small  $mY_s$ , and we conclude that the lightest mode always satisfies

$$m_1 \sim Y_s^{-1}$$
. (36)

B. Large 
$$-M^2$$

We can use the zeroth order term for X to compute the coordinate Y. However, the second order term  $E_1(y(Y)/\epsilon)$  is crucial to the computation of the effective potential in (25): after being differentiated twice, it becomes a zeroth order quantity. Actually, it is slightly more convenient to use the physical coordinate y. Letting  $\xi_m = a^{1/2}\psi_m$ , we have

$$\left(\partial_y^2 + \frac{m^2}{1 - \frac{y}{3}} + \frac{1}{12} \frac{\cos\frac{2y}{\epsilon}}{(1 - \frac{y}{3})^2}\right) \xi_m = 0.$$
 (37)

There is some hope of solving this equation in the limit that the regulator brane is brought very close to the first brane. To be specific, we suppose  $y_{\star} \sim \epsilon$ . Then letting  $y = \epsilon z$ , we obtain a Mathieu equation

$$\left(\partial_z^2 + A - 2q\cos 2z\right)\xi_m = 0,\tag{38}$$

where  $A = \epsilon^2 m^2$  and  $q = -\frac{1}{24} \epsilon^2$ , subject to  $\partial_z \xi_m(0) = \partial_z \xi_m(z_\star) = -\frac{1}{3} \epsilon$ . If we could find bound states with  $m \sim \mathcal{O}(\epsilon^n)$ , n > -1, it might be that  $my_\star \ll mr \ll 1$ , and this would be fatal for the Newtonian limit. As it happens, this does not occur. The solutions [9] to (38) are linear combinations of  $F_\nu(\pm z)$ , which for small q become

$$F_{\nu}(z) \simeq e^{i\nu z} \left[ 1 - \frac{1}{4}q \left( \frac{e^{2iz}}{\nu + 1} - \frac{e^{-2iz}}{\nu - 1} \right) \right],$$
 (39)

where  $A \simeq \nu^2 + \frac{1}{2}q^2/(v^2-1)$  for  $\nu$  real and non-integer. Then, one can show that it is not possible to satisfy the boundary conditions for small, real  $\nu$ . This implies that either  $\nu \sim 1$  or  $\nu$  is purely imaginary, i.e., in an instability band of the Mathieu equation. In either case,  $A \sim 1$ .

#### V. CONCLUSIONS

We have conducted two distinct perturbative analyses of brane world models that incorporate a massive bulk scalar field. First, we used nonlinear perturbation theory to find background solutions in the limits of small mass and large negative mass. In both cases, we found it was necessary to add a second brane to eliminate a singularity. Second, we considered tensor perturbations about these background solutions. We were able to show that the brane-bound observer will observe only slight modifications to Newtonian gravity in the case of a light bulk scalar field. This result also holds true for a bulk scalar field with large negative mass, which in some ways mimics a bulk cosmological constant. Even though such a bulk potential may be unphysical, it arises naturally in higher-derivative theories of gravity that are conformally related to scalar-tensor theories, including general relativity with scalar field matter. Thus our analysis sheds light on the viability of these theories in the context of bulk extra dimensions. We will make this connection

more rigorous in upcoming work [10]. We also look to study the stability of the two-brane system introduced here.

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